

# On the modeling of drift fluxes with self-consistent electric field in the SOLPS code.

O. Maj<sup>1</sup>

in collaboration with M. Restelli<sup>1</sup>, D. Coster<sup>1</sup>, E. Sonnendrücker<sup>1</sup>, T. Feher<sup>1</sup> and Juan Vicente Gutierrez Santacreu<sup>2</sup>

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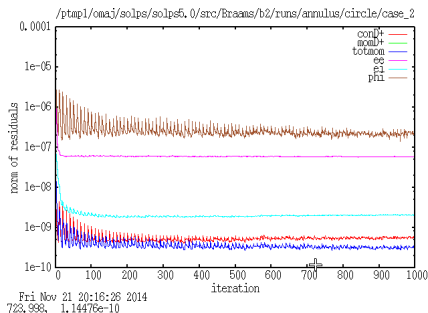
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SOLPS Optimization Meeting, Garching, Dec. 10th-12th, 2014

# Motivations:

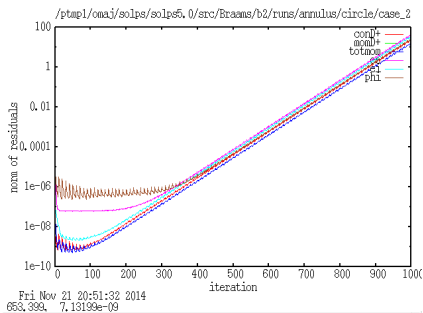
## Time-step limitations in SOLPS with drifts

Test case by David Coster - circular geometry (closed field lines).



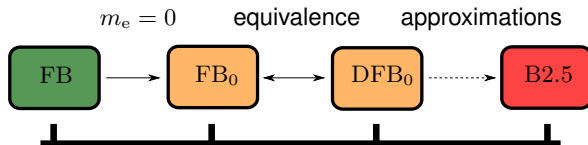
Time step  $\Delta t = 5.0 \times 10^{-7}$  s.

- Without drift physics, one observes fast convergence with  $\Delta t = 10^{-3}$  s.
- We aim to develop a stand-alone code as a test-bed for models and schemes.
- This motivates our study of the mathematical structure of the B2.5 model [Rozhansky et al. Nucl. Fus. (2001)].



Time step  $\Delta t = 8.0 \times 10^{-7}$  s.

- **The self-consistent electric potential in a hierarchy of multi-fluid models:**



- FB Full system of Braginskii equations
- $FB_0$  Quasi-neutral zero-electron-mass limit of FB
- $DFB_0$  Drift formulation equivalent to  $FB_0$
- B2.5 Model of the B2.5 code

- **Initial development of a test code (Marco Restelli):**

- ▶ exploring numerical methods for this family of fluid models;
- ▶ addressing basic issues (sensitivity to input data, noisy sources, etc ...).

## The self-consistent electric potential in a hierarchy of multi-fluid models.

### General idea:

- Anomalous fluxes are added *ad hoc* later: no derivation.
- Neutrals can enter either as sources or fluid species.
- Divergence-free terms are kept in the equation for clarity.
- Refrain from approximations as far as possible.
- Emphasis on the mathematical structure of the equations and possible sources of the instability.

# Full system of Braginskii equations (FB)

## Model equations

- Main equations of the model: for  $\alpha \in \text{Sp} = \{\text{various ion species, electrons}\}$ ,

$$\left\{ \begin{array}{l} \partial_t n_\alpha + \nabla \cdot (n_\alpha v_\alpha) = S_{n,\alpha}, \\ \partial_t (m_\alpha n_\alpha v_\alpha) + \nabla \cdot (m_\alpha n_\alpha v_\alpha \otimes v_\alpha + \pi_\alpha) \\ \qquad \qquad \qquad = -\nabla p_\alpha + e_\alpha n_\alpha \left( -\nabla \phi + \frac{v_\alpha \times B}{c} \right) + R_\alpha + S_{M,\alpha}, \\ \partial_t \left( \frac{3}{2} p_\alpha \right) + \nabla \cdot \left( \frac{3}{2} p_\alpha v_\alpha + q_\alpha \right) + p_\alpha \nabla \cdot v_\alpha + \pi_\alpha : \nabla v_\alpha = Q_\alpha + S_{T,\alpha}, \\ \nabla \cdot J = 0, \end{array} \right.$$

where  $J = \sum_{\alpha \in \text{Sp}} e_\alpha n_\alpha v_\alpha$  and  $S_{n,\alpha}$ ,  $S_{M,\alpha}$ , and  $S_{T,\alpha}$  are sources.

- Closure relations for  $\pi_\alpha$ ,  $R_\alpha$ ,  $Q_\alpha$ , and  $q_\alpha$ , satisfying

$$\sum_{\alpha \in \text{Sp}} R_\alpha = 0, \quad \sum_{\alpha \in \text{Sp}} (Q_\alpha + v_\alpha \cdot R_\alpha) = 0.$$

- The electric potential  $\phi$  is determined as a Lagrange multiplier for  $\nabla \cdot J = 0$ .
- Without sources and with appropriate boundary conditions, energy is conserved:

$$W(t) = \sum_{\alpha \in \text{Sp}} \int_{\Omega} \left( \frac{1}{2} m_\alpha n_\alpha |v_\alpha|^2 + \frac{3}{2} p_\alpha \right) dV = \text{constant},$$

as a consequence of  $\nabla \cdot J = 0$ .

Braginskii equations with zero electron mass (FB<sub>0</sub>)

## Model equations

- Main equations of the model: for  $a \in \text{Sp}_0 = \text{Sp} \setminus \{e\}$

$$\left\{ \begin{array}{l} \partial_t n_a + \nabla \cdot (n_a v_a) = S_{n,a}, \\ \partial_t (m_a n_a v_a) + \nabla \cdot (m_a n_a v_a \otimes v_a + \pi_a) \\ \quad = -\nabla p_a + e_a n_a \left( -\nabla \phi + \frac{v_a \times B}{c} \right) + R_a + S_{M,a}, \\ \partial_t \left( \frac{3}{2} p_a \right) + \nabla \cdot \left( \frac{3}{2} p_a v_a + q_a \right) + p_a \nabla \cdot v_a + \pi_a : \nabla v_a = Q_a + S_{T,a}, \\ \nabla \cdot J = 0, \\ n_e = \sum_{a \in \text{Sp}_0} Z_a n_a, \\ 0 = -\nabla p_e - e n_e \left( -\nabla \phi + \frac{v_e \times B}{c} \right) + R_e + S_{M,e}, \\ \partial_t \left( \frac{3}{2} p_e \right) + \nabla \cdot \left( \frac{3}{2} p_e v_e + q_e \right) + p_e \nabla \cdot v_e = Q_e + S_{T,e}, \quad (\pi_e = 0). \end{array} \right.$$

- Again,  $\phi$  is a Lagrange multiplier for  $\nabla \cdot J = 0$ .
- Again, the relevant energy is conserved

$$W(t) = \int_{\Omega} \left[ \sum_{a \in \text{Sp}_0} \left( \frac{1}{2} m_a n_a |v_a|^2 + \frac{3}{2} p_a \right) + \frac{3}{2} p_e \right] dV = \text{constant},$$

⇒ Energy conserving schemes derived by Juan Vicente Gutierrez Santacreu.

Braginskii equations with zero electron mass (FB<sub>0</sub>)

## Determining the electron velocity

- The electron velocity should be fully determined by the electron force balance

$$0 = -\nabla p_e - en_e(-\nabla\phi + \frac{v_e \times B}{c}) + R_e + S_{M,e}.$$

- The friction force  $R_e$  on electrons is crucial:

$$R_e = en_e(J_{\parallel}/\sigma_{\parallel} + J_{\perp}/\sigma_{\perp}) + R_T.$$

## Proposition

Given sufficiently regular  $n_e, p_e, n_a, v_a$  for  $a \in \text{Sp}_0$  and  $\phi$ , with both  $n_e, 1/n_e \in L^\infty$ , the electron force balance is equivalent to

$$J = \hat{\sigma}[-\nabla\phi + E_T],$$

where  $\hat{\sigma}$  is bounded and positive-definite, and  $E_T$  is a function of  $n_e, \nabla p_e, R_T, n_a, v_a$ ,

$$en_e E_T = \nabla p_e - R_T - S_{M,e} + \sum_{a \in \text{Sp}_0} e_a n_a v_a \times B/c,$$

and thus the electron velocity determined by  $en_e v_e = \sum_a e_a n_a v_a - J$ .

## Equivalent form of the perpendicular current density

- Total momentum balance equation for the model  $FB_0$ :

$$\partial_t \mathcal{P} + \nabla \cdot \mathcal{S} = -\nabla p + J \times B/c + S_M,$$

with momentum/momentum-flux pair

$$\mathcal{P} = \sum_{a \in Sp_0} m_a n_a v_a, \quad \mathcal{S} = \sum_{a \in Sp_0} m_a n_a v_a \otimes v_a + \pi_a,$$

where  $p = \sum_a p_a + p_e$  and  $S_M = \sum_a S_{M,a} + S_{M,e}$ .

- We can solve for  $J_\perp$  from the total momentum balance:

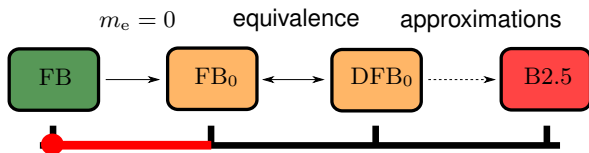
$$J_\perp = \underbrace{\frac{c}{|B|} b \times \nabla p}_{\text{diamagnetic current}} + \frac{c}{|B|} b \times [\partial_t \mathcal{P} + \nabla \cdot \mathcal{S} - S_M].$$

### Proposition

For a sufficiently regular solution,

$$J_\perp = [\hat{\sigma}(-\nabla\phi + E_T)]_\perp = \frac{c}{|B|} b \times \nabla p + \frac{c}{|B|} b \times [\partial_t \mathcal{P} + \nabla \cdot \mathcal{S} - S_M].$$





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# Drift velocity

## Basic ideas: a simple textbook example

- Euler's equation for an electrically charged fluid:

$$mn \frac{du}{dt} = -\nabla p + en \left( E + \frac{u \times B}{c} \right)$$

- The perpendicular part can be rewritten by solving for  $u_{\perp}$ :

$$\begin{aligned} u_{\perp} &= c \frac{E \times B}{B^2} + c \frac{B \times \nabla p}{enB^2} - \frac{mc}{eB^2} B \times \frac{du}{dt} \\ &= \underbrace{c \frac{E \times B}{B^2}}_{E \times B \text{ drift}} + \underbrace{c \frac{B \times \nabla p}{enB^2}}_{\text{diamagnetic drift } u_*} - \underbrace{\frac{1}{\omega_c} b \times \frac{du}{dt}}_{\text{inertia}} \end{aligned}$$

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$$= c \underbrace{\frac{E \times B}{B^2}}_{E \times B \text{ drift}} + c \underbrace{\frac{B \times \nabla p}{enB^2}}_{\text{diamagnetic drift } u_*} - \underbrace{\frac{1}{\omega_c} b \times \frac{du}{dt}}_{\text{inertia}}$$

initial guess  $u_{0\perp}$  for fixed-point iterations.

- This turns an initial/boundary value problem into a fixed-point problem.

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initial guess  $u_{0\perp}$  for fixed-point iterations.

- This turns an initial/boundary value problem into a fixed-point problem.
- Guiding-center drifts:

$$\nabla \cdot (nu_*) = \nabla \cdot \left[ -\frac{cp}{e} B \times \nabla \frac{1}{B^2} \right] + \frac{c}{e} \nabla \frac{p}{B^2} \cdot \nabla \times B.$$

## Drift velocity

### Drift formulation of the momentum balance equation

- Define the current densities

$$J_a^{(r)} = \frac{c}{|B|} b \times [\partial_t(m_a n_a v_a) + \nabla \cdot (m_a n_a v_a \otimes v_a + \pi_a) - S_{M,a}],$$

$$J_{\perp}^{(r)} = \sum_{a \in \text{SP}_0} J_a^{(r)} = J_{\perp} - \frac{cB \times \nabla p}{B^2},$$

where  $\{v_a\}_a \mapsto J_a^{(r)}$  is a linear operator acting on velocities  $\{v_a\}_a$ .

### Proposition

For every ion species  $a$ , the momentum equation

$$\partial_t(m_a n_a v_a) + \nabla \cdot (m_a n_a v_a \otimes v_a + \pi_a) = -\nabla p_a + e_a n_a (-\nabla \phi + \frac{v_a \times B}{c}) + R_a + S_{M,a},$$

is formally equivalent to the parallel momentum balance complemented with the fixed-point problem

$$v_{a\perp} = c \frac{B \times \nabla \phi}{B^2} + c \frac{B \times \nabla p_a}{e_a n_a B^2} - \frac{D_a}{T_a + Z_a T_e} \left[ \frac{\nabla_{\perp} p}{n_e} - \frac{3}{2} \nabla_{\perp} T_e \right] + \frac{J_a^{(r)}}{e_a n_a} + \frac{1}{\tau_e \omega_{ce}} \frac{b \times J_{\perp}^{(r)}}{en_e},$$

where  $D_a = \frac{1}{\tau_e \omega_{ce}} \frac{c}{e|B|} (T_a + Z_a T_e)$  is the collisional diffusion coefficient.

# Drift formulation of Braginskii equations (DFB<sub>0</sub>)

## Model equations

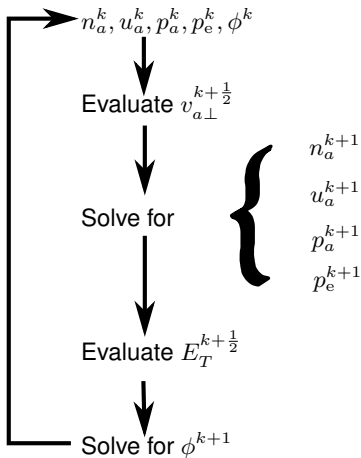
- Definition of the parallel velocity  $u_a = b \cdot v_a$ .
- Main equations of the model: for  $a \in \text{Sp}_0 = \text{Sp} \setminus \{e\}$

$$\left\{ \begin{array}{l} \partial_t n_a + \nabla \cdot (n_a (u_a b + v_{a\perp})) = S_{n,a}, \\ \partial_t (m_a n_a u_a) + \nabla \cdot (m_a n_a u_a (u_a b + v_{a\perp}) + \pi_a \cdot b) - m_a n_a (u_a b + v_{a\perp}) \cdot \nabla b \cdot v_{a\perp} \\ \quad - \pi_a : \nabla b = -b \cdot \nabla p_a - e_a n_a b \cdot \nabla \phi + b \cdot R_a + b \cdot S_{M,a}, \\ v_{a\perp} = c \frac{B \times \nabla \phi}{B^2} + c \frac{B \times \nabla p_a}{e_a n_a B^2} - \frac{D_a}{T_a + Z_a T_e} \left[ \frac{\nabla_{\perp} p}{n_e} - \frac{3}{2} \nabla_{\perp} T_e \right] + \frac{J_a^{(r)}}{e_a n_a} + \frac{1}{\tau_e \omega_{ce}} \frac{b \times J_{\perp}^{(r)}}{e n_e}, \\ \partial_t \left( \frac{3}{2} p_a \right) + \nabla \cdot \left( \frac{3}{2} p_a v_a + q_a \right) + p_a \nabla \cdot v_a + \pi_a : \nabla v_a = Q_a + S_{T,a}, \\ \partial_t \left( \frac{3}{2} p_e \right) + \nabla \cdot \left( \frac{3}{2} p_e v_e + q_e \right) + p_e \nabla \cdot v_e = Q_e + S_{T,e}, \\ \nabla \cdot [\hat{\sigma} (\nabla \phi - E_T)] = 0, \end{array} \right.$$

- Quasi-neutrality is implied.
- Both  $J$  and  $v_e$  are given explicitly as functions of the other variables.

# Drift formulation of Braginskii equations (DFB<sub>0</sub>)

## Tentative iterative scheme





# Drift formulation of Braginskii equations (DFB<sub>0</sub>)

## Choice of the equation for the potential

- Two equivalent forms of the perpendicular current

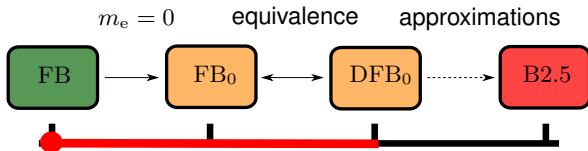
$$J_{\perp} = [\hat{\sigma}(-\nabla\phi + E_T)]_{\perp} = \frac{c}{|B|} b \times \nabla p + \frac{c}{|B|} b \times [\partial_t \mathcal{P} + \nabla \cdot \mathcal{S} - S_M].$$

- Two corresponding forms of the potential equation  $\nabla \cdot J = 0$ :

$$\nabla \cdot [\hat{\sigma}(\nabla\phi^{k+1} - E_T^{k+\frac{1}{2}})] = 0, \quad (\text{well-posed}),$$

$$\nabla \cdot [\sigma_{\parallel} \nabla_{\parallel} \phi^{k+1} - \tilde{J}^{k+\frac{1}{2}}] = 0, \quad (\text{ill-posed}).$$

- In addition,  $E_T$  does not involve the time derivative of  $v_a$ .
- However, in the “well-posed form” ambipolar terms are not automatically canceled.
- Coupling the potential equation with the electron pressure gradients?



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# Approximated model in the B2.5 code (B2.5)

## Model equations

- Main equations of the model: for  $a \in \text{Sp}_0 = \text{Sp} \setminus \{e\}$

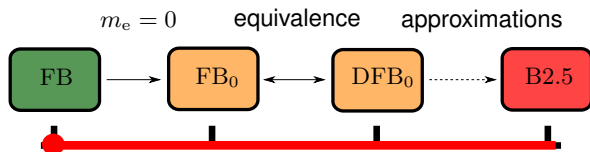
$$\left\{ \begin{array}{l} \partial_t n_a + \nabla \cdot (n_a (u_a b + v_{a\perp})) = S_{n,a}, \\ \partial_t (m_a n_a u_a) + \nabla \cdot (m_a n_a u_a (u_a b + v_{a\perp}) + \pi_a \cdot b) - m_a n_a (u_a b + v_{a\perp}) \cdot \nabla b \cdot v_{a\perp} \\ \quad - \pi_a : \nabla b = -b \cdot \nabla p_a - e_a n_a b \cdot \nabla \phi + b \cdot R_a + b \cdot S_{M,a}, \\ v_{a\perp} = c \frac{B \times \nabla \phi}{B^2} + c \frac{B \times \nabla p_a}{e_a n_a B^2} - \frac{D_a}{T_a + Z_a T_e} \left[ \frac{\nabla_{\perp} p}{n_e} - \frac{3}{2} \nabla_{\perp} T_e \right] + \frac{J_{\perp}^{(r)}}{e n_e}, \\ \partial_t \left( \frac{3}{2} p_a \right) + \nabla \cdot \left( \frac{3}{2} p_a v_a + q_a \right) + p_a \nabla \cdot v_a + \pi_a : \nabla v_a = Q_a + S_{T,a}, \\ \partial_t \left( \frac{3}{2} p_e \right) + \nabla \cdot \left( \frac{3}{2} p_e v_e + q_e \right) + p_e \nabla \cdot v_e = Q_e + S_{T,e}, \\ \nabla \cdot [\sigma_{\parallel} \nabla_{\parallel} \phi - \tilde{J}] = 0. \end{array} \right.$$

This reduces to the model by Rozhansky et al. [Nucl. Fus. (2001)].

- Approximations in the drift velocity (break energy conservation):

$$\underbrace{\frac{J_a^{(r)}}{e_a n_a} \approx \frac{J_{\perp}^{(r)}}{e n_e}}_{\text{single ion species}}, \quad \underbrace{\frac{1}{\tau_e \omega_{ce}} \frac{b \times J_{\perp}^{(r)}}{e n_e}}_{\text{higher-order term neglected}} \approx 0.$$

- Remark: The potential equation in the iterative scheme becomes ill-defined.



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- Relationship among a class of multi-fluid models.
- An extended version of the B2.5 model, which is equivalent to Braginskii equations with zero electron mass and quasi-neutrality.
- Two equivalent forms of the potential equation.
- Possible sources of the step-size limitations in B2.5:
  - ▶ Ill-defined boundary value problem for the potential.
  - ▶ Fixed point iteration.

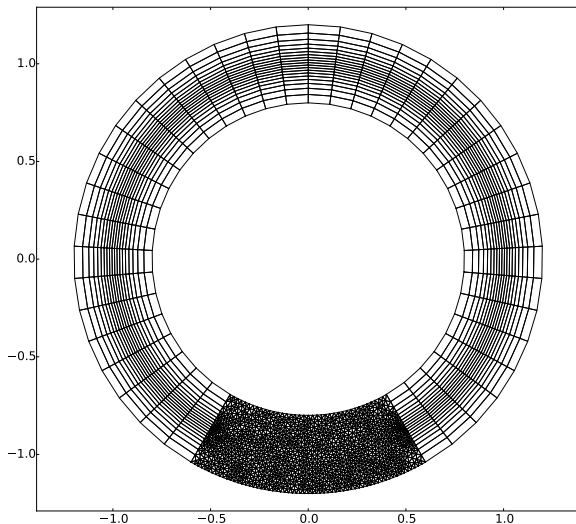
# Initial development of a new code

## Concept of the new code (by Marco Restelli)

- A code for multi-fluid models of the plasma edge which
  - ▶ provides a test-bed for numerical schemes;
  - ▶ allows us to explore the various formulations and models;
  - ▶ possibly includes uncertainty quantification (perturbation of data, noise, ...).
- Geometry:
  - ▶ Unstructured grid in generic coordinates (avoid local coordinate patches).
  - ▶ Possibility of flux-surface alignment and grid refinement.
- Space discretization:
  - ▶ Finite element method on unstructured grids.
  - ▶ SUPG stabilization of the convective terms.
  - ▶ MPI parallelization with domain decomposition.
  - ▶ MUMPS/PASTIX/PETSC/... libraries to solve the linear systems.
- Time discretization:
  - ▶ Standard diagonally implicit;
  - ▶ Energy-conserving slitting schemes (Juan Vicente Gutierrez Santacreu).

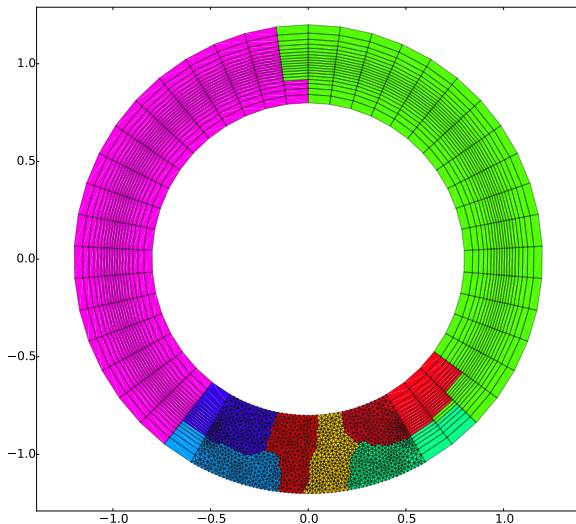
# Initial development of a new code

Example of grid in circular geometry (by Marco Restelli)



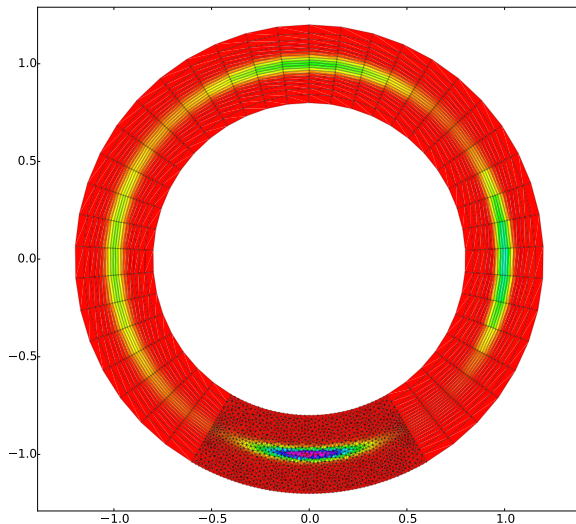
# Initial development of a new code

## Partition of the grid (by Marco Restelli)



# Initial development of a new code

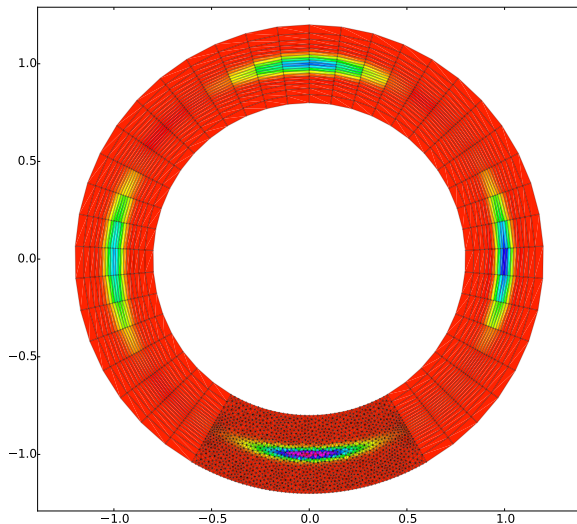
Parallel advection - first-order upwind stabilization (by Marco Restelli)





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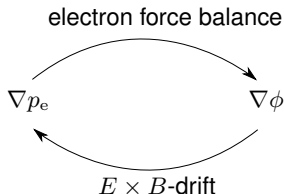
Parallel advection - second-order upwind stabilization (by Marco Restelli)



## Open discussion:

### Testing the coupling between the potential and the electron pressure gradient

- Sketch of the coupling:



- Minimal set of equations:

$$\begin{cases} \partial_t n + \nabla \cdot (n v_E - D \nabla_{\perp} n) = S, \\ \partial_t \frac{3}{2} p_e + \nabla \cdot \left[ \frac{3}{2} p_e (v_E - J / (e n_e)) \right] + p_e \nabla \cdot (v_E - J / (e n_e)) = 0, \\ \nabla \cdot J = 0, \quad J = -\sigma_{\parallel} \nabla_{\parallel} \phi - \sigma_{\text{reg}} \nabla_{\perp} \phi + \hat{\sigma} (\nabla p_e - R_T) / (e n_e), \end{cases}$$

where  $S$  is a possibly noisy source,  $n_e = Z n$ ,  $p_e = n_e T_e$  and

$$v_E = c \frac{B \times \nabla \phi}{B^2}, \quad R_T = -0.71 n_e \nabla_{\parallel} T_e - \frac{3 n_e}{2 \omega_{ce} \tau_e} b \times \nabla T_e.$$

## Open discussion:

### Testing the coupling between the potential and parallel momentum

- Minimal set of equations:

$$\begin{cases} \partial_t n + \nabla \cdot (nub + v_d) = S^n, \\ \partial_t (mnu) + \frac{1}{R} \nabla \cdot [Rmnu(ub + v_d) - R\nu \nabla u] = -\nabla_{\parallel} p + S_{\parallel}^M, \\ \nabla \cdot (\sigma \nabla \phi) = \nabla \cdot f(n, \nabla_{\parallel} p_e, \nabla_{\parallel} T_e, \nabla p), \end{cases}$$

with prescribed temperature profiles and

$$\begin{aligned} p_e &= n_e T_e, & p_i &= n T_i, & p &= p_i + p_e, \\ v_d &= c \frac{B \times \nabla \phi}{B^2} + c \frac{B \times \nabla p_i}{Z e n B^2} - \frac{D^n \nabla n}{n} - \frac{D^p \nabla p_i}{n}, \\ f &= \sigma_{\parallel} \left( \frac{\nabla_{\parallel} p_e}{e n_e} + 0.71 \nabla_{\parallel} T_e / e \right) b + c \frac{B \times \nabla p}{B^2}. \end{aligned}$$

## Backup slides

## Full system of Braginskii equations (FB)

## Energy conservation

## Proposition

A solution  $n_\alpha, v_\alpha, p_\alpha, \phi$  is such that

$$\partial_t \mathcal{E} + \nabla \cdot \mathcal{F} = -\nabla \phi \cdot J + \sum_{\alpha \in \text{Sp}} (S_{T,\alpha} + v_\alpha \cdot S_{M,\alpha} - \frac{1}{2} m_\alpha |v_\alpha|^2 S_{n,\alpha}),$$

where the energy/energy-flux pair is

$$\mathcal{E} = \sum_{\alpha \in \text{Sp}} (\frac{1}{2} m_\alpha n_\alpha |v_\alpha|^2 + \frac{3}{2} p_\alpha), \quad \mathcal{F} = \sum_{\alpha \in \text{Sp}} \left[ (\frac{1}{2} m_\alpha n_\alpha |v_\alpha|^2 + \frac{5}{2} p_\alpha) v_\alpha + q_\alpha + \pi_\alpha \cdot v_\alpha \right].$$

If  $S_n = 0, S_M = 0, S_T = 0$  and the normal components  $\mathcal{F}_n$  and  $J_n$  vanish on  $\partial\Omega$ ,

$$\int_{\Omega} \mathcal{E}_0 dV = \sum_{\alpha \in \text{Sp}} \int_{\Omega} (\frac{1}{2} m_\alpha n_\alpha |v_\alpha|^2 + \frac{3}{2} p_\alpha) dV = \text{constant}.$$

## Proposition

A solution  $n_\alpha, v_\alpha, p_\alpha, \phi$  satisfies the energy balance

$$\partial_t \mathcal{E}_0 + \nabla \cdot \mathcal{F}_0 = -\nabla \phi \cdot J + \text{sources}$$

with energy/energy-flux pair

$$\mathcal{E}_0 = \sum_{a \in \text{Sp}_0} \left( \frac{1}{2} m_a n_a |v_a|^2 + \frac{3}{2} p_a \right) + \frac{3}{2} p_e,$$

$$\mathcal{F}_0 = \sum_{a \in \text{Sp}_0} \left[ \left( \frac{1}{2} m_a n_a |v_a|^2 + \frac{5}{2} p_a \right) v_a + q_a + \pi_a \cdot v_a \right] + \frac{5}{2} p_e v_e + q_e.$$

- Energy-conserving splitting schemes for this system have been derived by Juan Vicente Gutierrez-Santacreu.

## Sketch of the proof of the first expression for $J$ and $v_e$ .

Parallel projection:

$$0 = -\nabla_{\parallel} p_e + en_e \nabla_{\parallel} \phi + en_e J_{\parallel} / \sigma_{\parallel} + R_{T\parallel} + S_{M,e\parallel},$$

which gives

$$J_{\parallel} = \sigma_{\parallel} [-\nabla \phi + E_{T\parallel}], \quad E_{T\parallel} = (\nabla_{\parallel} p_e - R_{T\parallel} - S_{M,e\parallel}) / (en_e).$$

The perpendicular projection:

$$(I - \kappa b \times) J_{\perp} = -\sigma_{\perp} [\nabla_{\perp} \phi + E_{T\perp}], \quad \kappa = \frac{\sigma_{\perp} |B|}{en_e c},$$

where

$$E_{T\perp} = (\nabla_{\perp} p_e - R_{T\perp} - S_{M,e\perp} + \sum_{a \in \text{Sp}_0} e_a n_a v_a \times B/c) / (en_e).$$

The result follows from the fact that the matrix  $(I - \kappa b \times)$  is invertible when restricted to vectors perpendicular to  $b$ . Also  $(I - \kappa b \times)$  restricted to perpendicular vectors is positive-definite as  $J_{\perp} \cdot (I - \kappa b \times) J_{\perp} = |J_{\perp}|^2$ , hence so is its inverse. □

## Sketch of the proof on the drift velocity.

Recall the definition (extended to multiple ion species with quasi-neutrality)

$$R_a = -e_a n_a (J_{\parallel} / \sigma_{\parallel} + J_{\perp} / \sigma_{\perp}) - R_T, \quad R_T = -0.71 n_a Z_a \nabla_{\parallel} T_e - \frac{3 Z_a n_a}{2 \omega_{ce} \tau_e} b \times \nabla T_e.$$

Multiply the momentum equation by  $\frac{c}{e_a n_a B^2} B \times$  and solve for  $v_{a\perp}$ ,

$$v_{a\perp} = c \frac{B \times \nabla \phi}{B^2} + c \frac{B \times \nabla p_a}{e_a n_a B^2} + \frac{3}{2 \omega_{ce} \tau_e} \frac{c}{e |B|} \nabla_{\perp} T_e + c \frac{B \times J_{\perp}}{\sigma_{\perp} B^2} + \frac{c}{e_a n_a B^2} B \times [\partial_t (m_a n_a v_a) + \nabla \cdot (m_a n_a v_a \otimes v_a + \pi_a) - S_{M,a}].$$

Upon substituting the expression

$$J_{\perp} = [\hat{\sigma}(-\nabla \phi + E_T)]_{\perp} = \frac{c}{|B|} b \times \nabla p + \frac{c}{|B|} b \times [\partial_t \mathcal{P} + \nabla \cdot \mathcal{S} - S_M]$$

the diamagnetic current combines with the  $\nabla_{\perp} T_e$ -term to give the classical diffusion, thus leaving  $J_{\perp}^{(r)}$ . The expression for  $D_a$  follows from  $\sigma_{\perp} = n_e e^2 \tau_e / m_e$ , and the definition of partial temperature  $T_a + Z_a T_e$ ,

$$p = \sum_{\alpha \in \text{Sp}} n_{\alpha} (k_B T_{\alpha}) = \sum_{\alpha \in \text{Sp}_0} n_{\alpha} k_B (T_{\alpha} + Z_{\alpha} T_e).$$

□