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Magnetohydrodynamic Properties of Nominally Axisymmetric Systems with 3D Helical Core

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MOTIVATION

Manifestation of internal 3D structures in axisymmetric devices:

- SHAx states in RFX-mod
 - -R. Lorenzini et al., Nature Physics 5 (2009) 570
- "Snakes" in JET
 - -A. Weller et al., Phys. Rev. Lett. **59** (1987) 2303
- Disappearance of sawteeth but continuous dominantly n = 1 mode in TCV at high elongation and current -Y. Camenen et al., Nucl. Fusion 47 (2007) 586
- Change of sawteeth from kink-like to quasi-interchange-like with plasma shaping in DIII-D
 - -E. A. Lazarus et al., Plasma Phys. Contr. Fusion 48 (2006) L65
- Long-lived saturated modes in MAST
 –I. T. Chapman et al., Nucl. Fusion 50 (2010) 045997



THEORY REVIEW

- Analytic investigations of nonlinearly saturated m = 1, n = 1 ideal MHD instability
 - -Avinash, R.J. Hastie, J.B. Taylor, Phys. Rev. Lett. 59 (1987) 2647
 - -M.N. Bussac, R. Pellat, Phys. Rev. Lett. 59 (1987) 2650
 - -F.L. Waelbroeck, Phys. Fluids **B 59** (1989) 499
- Large scale simulations of nonlinearly saturated MHD instability -L.A. Charlton et al., Phys. Fluids B 59 (1989) 798
 -H. Lütjens, J.F. Luciani, J. Comput. Phys. 227 (2008) 6944
- Bifurcated equilibria due to ballooning modes with the NSTAB code
 –P. Garabedian, Proc. Natl. Acad. Sci. USA 103 (2006) 19232
- RFX-mod SHAx MHD equilibria

-D. Terranova et al., in Plasma Phys. Contr. Fusion (2010)

 Bifurcated tokamak equilibria similar to a saturated internal kink –W.A. Cooper et al., Phys. Rev. Lett. 105 (2010) 035003



OUTLINE

- We investigate the proposition that the "instability" structures observed in the experiments constitute in reality new equilibrium states with 3D character
- 3D magnetohydrodynamic (MHD) fixed boundary equilibria with imposed nested flux surfaces are investigated with: VMEC2000
 - -S. P. Hirshman, O. Betancourt, J. Comput. Phys. **96** (1991) 99 ANIMEC
 - -W. A. Cooper et al., Comput. Phys. Commun. 180 (2009) 1524
- Linear MHD stability computed with TERPSICHORE
 –D. V. Anderson et al., Int. J. Supercomp. Appl. 4 (1990) 33
- MHD equilibria with 3D internal helical structures computed for RFX-mod, TCV, ITER (hybrid scenario), MAST and JET (Snakes)
- Linear ideal MHD stability calculated for RFX-mod



Momentum balance equation

 $\nabla p = j \times B$

Parallel projection

$$\boldsymbol{B} \boldsymbol{\cdot} \boldsymbol{\nabla} p = 0 \Longrightarrow p = p(\psi)$$

Binormal projection

 $\boldsymbol{j}\boldsymbol{\cdot}\boldsymbol{\nabla}\psi=0\Longrightarrow I=I(\psi)$

Radial projection (Grad-Shafranov equation)

 $\Delta^* \psi = -R^2 p'(\psi) - I(\psi) I'(\psi)$

 $\triangleright \ \Delta^*$ operator to solve for $\psi=\psi(R,Z)$ directly

$$\Delta^* = R \frac{\partial}{\partial R} \left(\frac{1}{R} \frac{\partial}{\partial R} \right) + \frac{\partial^2}{\partial Z^2}$$

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- Impose nested magnetic surfaces and single magnetic axis
- Minimise energy of the system

$$W = \int \int \int d^3x \left(\frac{B^2}{2\mu_0} + \frac{p_{\parallel}(s,B)}{\Gamma-1}\right)$$

Solve inverse equilibrium problem : R = R(s, u, v) , Z = Z(s, u, v).

Variation of the energy

$$\frac{dW}{dt} = - \int \int \int ds du dv \left[F_R \frac{\partial R}{\partial t} + F_Z \frac{\partial Z}{\partial t} + F_\lambda \frac{\partial \lambda}{\partial t} \right] - \int \int_{s=1}^{\infty} du dv \left[R \left(p_\perp + \frac{B^2}{2\mu_0} \right) \left(\frac{\partial R}{\partial u} \frac{\partial Z}{\partial t} - \frac{\partial Z}{\partial u} \frac{\partial R}{\partial t} \right) \right]$$



▶ The MHD forces are

$$F_{R} = \frac{\partial}{\partial u} [\sigma \sqrt{g} B^{u} (\boldsymbol{B} \cdot \boldsymbol{\nabla} R)] + \frac{\partial}{\partial v} [\sigma \sqrt{g} B^{v} (\boldsymbol{B} \cdot \boldsymbol{\nabla} R)]$$

$$- \frac{\partial}{\partial u} \Big[R \frac{\partial Z}{\partial s} \Big(p_{\perp} + \frac{B^{2}}{2\mu_{0}} \Big) \Big] + \frac{\partial}{\partial s} \Big[R \frac{\partial Z}{\partial u} \Big(p_{\perp} + \frac{B^{2}}{2\mu_{0}} \Big) \Big]$$

$$+ \frac{\sqrt{g}}{R} \Big[\Big(p_{\perp} + \frac{B^{2}}{2\mu_{0}} \Big) - \sigma R^{2} (B^{v})^{2} \Big]$$

$$F_{z} = \frac{\partial}{\partial u} [\sigma \sqrt{g} B^{u} (\boldsymbol{B} \cdot \boldsymbol{\nabla} Z)] + \frac{\partial}{\partial v} [\sigma \sqrt{g} B^{v} (\boldsymbol{B} \cdot \boldsymbol{\nabla} Z)]$$

$$+ \frac{\partial}{\partial u} \Big[R \frac{\partial R}{\partial s} \Big(p_{\perp} + \frac{B^{2}}{2\mu_{0}} \Big) \Big] - \frac{\partial}{\partial s} \Big[R \frac{\partial R}{\partial u} \Big(p_{\perp} + \frac{B^{2}}{2\mu_{0}} \Big) \Big]$$

 \triangleright The λ force equation minimises the spectral width and corresponds to the binormal projection of the momentum balance at the equilibrium state.

$$F_{\lambda} = \Phi'(s) \left[\frac{\partial(\sigma B_v)}{\partial u} - \frac{\partial(\sigma B_u)}{\partial v} \right]$$

 $\triangleright~$ For isotropic pressure $p_{\parallel}=p_{\perp}=p$ and $\sigma=1/\mu_{0}.$



- \triangleright Use Fourier decomposition in the periodic angular variables u and v and a special finite difference scheme for the radial discretisation
- An accelerated steepest descent method is applied with matrix preconditioning to obtain the equilibrium state
- The radial force balance is a diagnostic of the accuracy of the equilibrium state in this approach

$$\left\langle \frac{F_s}{\Phi'(s)} \right\rangle = -\left\langle \frac{1}{\Phi'(s)} \frac{\partial p_{\parallel}}{\partial s} \right|_B \right\rangle - \frac{\partial}{\partial s} \left\langle \frac{\sigma B_v}{\sqrt{g}} \right\rangle - \iota(s) \frac{\partial}{\partial s} \left\langle \frac{\sigma B_u}{\sqrt{g}} \right\rangle$$

 $\triangleright \langle \cdot \cdot \cdot \rangle$ denotes a flux surface average

$$\langle A \rangle = \frac{L}{(2\pi)^2} \int_0^{2\pi/L} dv \int_0^{2\pi} du \sqrt{g} A(s, u, v)$$

▶ This model is implemented in the ANIMEC code, an anisotropic pressure extension of the VMEC2000 code. *L* is the number of toroidal field periods.



• Contours of constant parallel current density at a various cross sections spanning half a field period. The number of periods is 7.





- Fixed axisymmetric boundary equilibrium studies are explored.
- TCV boundary description: $R_b = 0.8 + 0.2 \cos u + 0.06 \cos 2u$; $Z_b = 0.48 \sin u$
- MAST, JET boundary: $R_b = R_0 + a \cos(u + \delta \sin u + \tau \sin 2u)$; $Z_b = Ea \sin u$ MAST: $R_0 = 0.9m$, a = 0.54m, E = 1.744, $\delta = 0.3985$, $\tau = 0.1908$ JET: $R_0 = 2.96m$, a = 1.25m, E = 1.68, $\delta = 0.3$, $\tau = 0$



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Bifurcated equilibria in TCV

- Selection of q-profiles that yield bifurcated equilibria in TCV.
- Boundary description: $R_b = 0.8 + 0.2 \cos u + 0.06 \cos 2u$, $Z_b = 0.48 \sin u$.



TCV toroidal flux contours at various cross sections

• TCV toroidal magnetic flux contours with prescribed $\iota = 0.9 + 0.2s - 0.8s^6$ profile.



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- Helical axis displacement and energy difference as function of q_{min} .
- $q(s) = [0.9 + \alpha_1 s (0.6 + \alpha_1) s^6]^{-1}$, $\alpha_1 = 0.16 \to 0.32$.





- Flat core pressure and q-profile with weak shear reversal
- $q(s) = (0.9 + 0.3s s^4)^{-1}$. $p(s) = p_0(1 + 0.410227s^2 - 14.1988s^4 + 29.6253s^6 - 22.9512s^8 + 6.1152s^{10})$.





ITER equilibrium profiles

- Prescribe mass profile and toroidal current profile. $p(s) \sim \mathcal{M}(s) [\Phi'(s)]^{\Gamma}$
- Equilibria have toroidal current 13 14MA, $B_t = 4.6T$, $\langle \beta \rangle \simeq 2.9\%$



• Contours of constant pressure of an ITER hybrid scenario equilibrium with 13.3MA toroidal plasma current

ITER pressure contours at various cross sections



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• Define helical excursion parameter

$$\delta_H = \frac{\sqrt{R_{01}^2(s=0) + Z_{01}^2(s=0)}}{a}$$

• Convergence of δ_H with $N_r =$ number of radial grid points



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CRPP ITER pressure contours as a function of plasma current

• Contours of constant pressure at the cross section with toroidal angle $v=2\pi/3$



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Helical core ITER equilibria

• Variation of the helical axis distortion parameter δ_H with respect to the toroidal current and corresponding variation with respect to q_{min} .



MAST pressure contours at various cross sections

• Contours of constant pressure of a MAST equilibrium





JET "snake" equilibrium profiles

- Prescribe mass profile and toroidal current profile.
- Equilibrium has toroidal current 3.85MA, $B_t=3.1T$, $\langle\beta\rangle\simeq 2.3\%$



\Box JET pressure, mod-B contours at various cross sections





Internal potential energy

$$\delta W_p = \frac{1}{2} \int \int \int d^3x \Big[C^2 + \Gamma p | \boldsymbol{\nabla} \cdot \boldsymbol{\xi} |^2 - D | \boldsymbol{\xi} \cdot \boldsymbol{\nabla} s |^2 \Big]$$

> Use Boozer coordinates

$$\boldsymbol{\xi} = \sqrt{g} \boldsymbol{\xi}^{s} \boldsymbol{\nabla} \boldsymbol{\theta} \times \boldsymbol{\nabla} \boldsymbol{\phi} + \eta \frac{(\boldsymbol{B} \times \boldsymbol{\nabla} s)}{B^{2}} + \left[\frac{J(s)}{\Phi'(s)B^{2}} \eta - \mu \right] \boldsymbol{B}$$

Fourier decomposition in angular variables

$$\xi^{s}(s,\theta,\phi) = \sum_{\ell} s^{-q_{\ell}} X_{\ell}(s) sin(m_{\ell}\theta - n_{\ell}\phi + \Delta)$$
$$\eta(s,\theta,\phi) = \sum_{\ell} Y_{\ell}(s) cos(m_{\ell}\theta - n_{\ell}\phi + \Delta)$$

A hybrid finite element method is applied for the radial discretisation. In the 3D TERPSICHORE stability code, COOL finite elements based on variable order Legendre polynomials have been implemented. The order of the polynomial is labelled with *p*.



MHD stability in **RFX-mod**

• Ideal MHD stability with respect to n = 8 family of modes



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Eigenvalue Convergence with p

• λ convergence for core q'/q < 0

for core q'/q > 0





- The three leading Fourier amplitudes of the radial component of the displacement vector ξ^s_{mn} with w/a=1.198 and p=5

for core
$$q'/q < 0$$
 for core $q'/q > 0$





Summary and Conclusions — equilibrium

- Nominally axisymmetric Reversed Field Pinch and Tokamak systems can develop MHD equilibrium bifurcations that lead to the formation of core helical structures.
- In RFX-mod, the development of a SHAx equilibrium state is computed with a seven-fold toroidally periodic structure when q in the core $\sim 1/7.$
- In Tokamak devices, reversed magnetic shear (sometimes just very flat extended low shear) with $q_{min} \sim 1$ can trigger a bifurcated solution with a core helical structure similar to a saturated m = 1, n = 1 internal kink.
- We have computed these 3D core helical states in TCV, ITER, MAST and JET. The JET "snake" phenomenon is reproduced with our model.

Summary and Conclusions — MHD stability

- Brief periods in which the relatively quiescent SHAx state in RFXmod relaxes to a turbulent multiple helicity state are observed -R. Lorenzini et al., Nature Physics 5 (2009) 570.
- We have investigated the ideal MHD stability of SHAx equilibria by examining mode structures that break the m=1,n=7 periodicity of the system.
- Either a drop in q well below 1/8 or the disappearance of core shear reversal triggers ideal MHD modes dominated by m = 1, n = 8 coupled with m = 2, n = 15 components.
- In tokamaks, the issue of MHD stability is complicated by the fact that any mode to be investigated is in principle also a component of the equilibrium state. Possible exceptions: local ballooning/Mercier modes, external kink modes, stellarator-symmetry breaking modes.

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Summary and Conclusions

- The 3D helical core equilibrium states in nominally axiymmetric systems that have been obtained constitute a paradigm shift for which the tools developed for stellarators in MHD stability, kinetic stability, drift orbits, wave propagation or heating, neoclassical transport, gyrokinetics, etc become applicable and necessary to more accurately evaluate magnetic confinement physics phenomena.
- The constraint of nested magnetic flux surfaces and absence of Xpoints in our model preclude the generation of equilibrium states with magnetic islands. Saturated tearing modes could be investigated with SIESTA, PIES or HINT.

• Contours of constant pressure of an ITER hybrid scenario equilibrium with 13.3MA toroidal plasma current

ITER pressure contours at various cross sections



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CRPPITER pressure contours as a function of plasma current

• Contours of constant pressure at the cross section with toroidal angle $v = 2\pi/3$



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• Contours of constant parallel current density at a various cross sections spanning half a field period. The number of periods is 7.



CRPP TCV toroidal flux contours at various cross sections

• TCV toroidal magnetic flux contours with prescribed $\iota = 0.9 + 0.2s - 0.8s^6$ profile.



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0.6

0.8

 $v = \pi$

v=π

v=π

1.2

1

1

1.2

0.8 R

0.6



- Prescribe mass profile and toroidal current profile.
- Equilibrium has toroidal current 0.34MA, $B_t=0.4T$, $\langle \beta
 angle \simeq 6.2\%$



MAST pressure contours at various cross sections

• Contours of constant pressure of a MAST equilibrium





Variational energy principle

$$\delta W_P + \delta W_V - \omega^2 \delta W_K = 0$$

internal potential energy

$$\delta W_p = \frac{1}{2} \int \int \int d^3x \Big[C^2 + \Gamma p | \boldsymbol{\nabla} \cdot \boldsymbol{\xi} |^2 - D | \boldsymbol{\xi} \cdot \boldsymbol{\nabla} s |^2 \Big]$$

Stabilising perturbed magnetic field

$$\boldsymbol{C} = \boldsymbol{\nabla} \times (\boldsymbol{\xi} \times \boldsymbol{B}) + \frac{\boldsymbol{j} \times \boldsymbol{\nabla} s}{|\boldsymbol{\nabla} s|^2} (\boldsymbol{\xi} \cdot \boldsymbol{\nabla} s)$$

Instability driving term

$$D = \frac{2(\boldsymbol{j} \times \boldsymbol{\nabla} s) \cdot (\boldsymbol{B} \cdot \boldsymbol{\nabla}) \boldsymbol{\nabla} s}{|\boldsymbol{\nabla} s|^4}$$

▹ Vacuum energy

$$\delta W_V = \frac{1}{2} \int \int \int d^3x \Big| \boldsymbol{\nabla} \times \boldsymbol{A} \Big|^2$$

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▷ The magnetohydrodynamic instability driving terms correspond to ballooning/interchange (δW_{BI}) and kink (δW_J) structures

$$\begin{split} \delta W_{BI} &= -\frac{1}{2} \int_{0}^{1} ds \int_{0}^{\frac{2\pi}{L_{s}}} d\phi \int_{0}^{2\pi} d\theta p'(s) \bigg[\frac{\sqrt{g}p'(s) + \psi''(s)J(s) - \Phi''(s)I(s)}{B^{2}} \\ &\quad -\frac{\partial\sqrt{g}}{\partial s} \bigg] (\xi^{s})^{2} \\ &\quad + \int_{0}^{1} ds \int_{0}^{\frac{2\pi}{L_{s}}} d\phi \int_{0}^{2\pi} d\theta p'(s) \frac{B_{s}}{B^{2}} \xi^{s}(\sqrt{g} \boldsymbol{B} \cdot \boldsymbol{\nabla} \xi^{s}) \\ \delta W_{J} &= -\frac{1}{2} \int_{0}^{1} ds \int_{0}^{\frac{2\pi}{L_{s}}} d\phi \int_{0}^{2\pi} d\theta \bigg[\frac{\sqrt{g}B^{2}}{|\boldsymbol{\nabla} s|^{2}} \bigg(\frac{\boldsymbol{j} \cdot \boldsymbol{B}}{B^{2}} \bigg) + \psi'(s) \Phi''(s) - \Phi'(s) \psi''(s) \bigg] \\ &\quad \times \bigg(\frac{\boldsymbol{j} \cdot \boldsymbol{B}}{B^{2}} \bigg) (\xi^{s})^{2} \\ &\quad - \int_{0}^{1} ds \int_{0}^{\frac{2\pi}{L_{s}}} d\phi \int_{0}^{2\pi} d\theta \bigg(\frac{\boldsymbol{j} \cdot \boldsymbol{B}}{B^{2}} \bigg) h_{s} \xi^{s}(\sqrt{g} \boldsymbol{B} \cdot \boldsymbol{\nabla} \xi^{s}) \end{split}$$



Perturbation Expansion

> Use Boozer coordinates

$$\boldsymbol{\xi} = \sqrt{g}\xi^{s}\boldsymbol{\nabla}\theta \times \boldsymbol{\nabla}\phi + \eta \frac{(\boldsymbol{B} \times \boldsymbol{\nabla}s)}{B^{2}} + \left[\frac{J(s)}{\Phi'(s)B^{2}}\eta - \mu\right]\boldsymbol{B}$$

Fourier decomposition in angular variables

$$\xi^{s}(s,\theta,\phi) = \sum_{\ell} s^{-q_{\ell}} X_{\ell}(s) sin(m_{\ell}\theta - n_{\ell}\phi + \Delta)$$
$$\eta(s,\theta,\phi) = \sum_{\ell} Y_{\ell}(s) cos(m_{\ell}\theta - n_{\ell}\phi + \Delta)$$

- A hybrid finite element method is applied for the radial discretisation. In the 3D TERPSICHORE stability code, COOL finite elements based on variable order Legendre polynomials have been implemented.
- $\triangleright\,$ For completeness, the expression for the geometric h_s term related to local shear is

$$h_s = -\frac{1}{|\boldsymbol{\nabla} s|^2} \left[I(s) \frac{g_{s\theta}}{\sqrt{g}} + J(s) \frac{g_{s\phi}}{\sqrt{g}} \right]$$



• The problem reduces to a special block pentadiagonal matrix eigenvalue equation $\mathcal{AX} = \lambda \mathcal{BX}$ that is solved with the PAMERA code (inverse vector iteration).





MHD Equilibrium Profiles

• Inverse rotational transform profiles

pressure profile





Wall Stabilisation Effects



for core q'/q > 0





Structure of δW_J

• The structure of the kink driving energy δW_J for core q'/q > 0 and w/a = 1.198 at three cross sections covering half of a field period (1/14th of the torus)





• The potential energy δW_p profiles for w/a = 1.198 and 1.395 and the three leading ξ^s_{mn} components for w/a = 2.976 for core q'/q > 0





• The kink mode driving energy δW_J and the ballooning/interchange driving energy δW_{BI} profiles with core q'/q > 0 at different conducting wall positions





Structure of δW_J

• The structure of the kink driving energy δW_J for core q'/q < 0 and w/a = 2.976 at three cross sections covering half of a field period (1/14th of the torus)





- Core magnetic shear reversed helical equilibrium states are essentially stable to ideal MHD for conducting wall to plasma diameter ratios w/a < 1.2. The helical states with monotonic q-profile are significantly more unstable. The periodicity breaking modes are dominantly m = 1, n = 8 coupled with m = 2, n = 15 components.
- For w/a > 1.2, global unstable kink mode structures are triggered. These kink modes are driven by the Ohmic current. The drive for ballooning and Pfirsch-Schlüter current modes is very weak. The dominant mode structure is a nonresonant m = 1, n = 6 component and is basically internal with a finite edge amplitude. Coupling with toroidal sidebands constitutes a significant contribution.
- Future work: applications to Helical-RFP states with edge toroidal magnetic field reversal.



- TERPSICHORE is a free-boundary fluid linear MHD stability code for 3D stellarator configurations with nested flux surfaces. The models treated encompass ideal MHD and extensions to anisotropic pressure (W. A. Cooper et al., PPCF 49 (2002) 1177).
- The TERPSICHORE code was developed based on a Fourier decomposition in the Boozer magnetic coordinate angular variables and on a radial discretisation with lowest order nonconforming hybrid finite elements (piecewise linear and constant) (D. V. Anderson et al., J. Int. Supercomp. Appl. 4 (1990) 34-47.)
- Now extended with the COOL finite element formulation to improve the radial discretisation. The basis functions are expanded in terms of Legendre polynomials of arbitrary order.

of mode structures that break this periodicity. In particular, we investigate the impact of core magnetic shear reversal on stability.

Radial Discretisation with the COOL method

Radial domain

$$s = s_{j-1/2} + \frac{\Delta s}{2}r \quad ; \quad -1 \le r \le 1$$
$$r = \frac{2}{\Delta s}(s - s_{j-1/2})$$

 \triangleright Basis functions applied to each interval centred about $s_{j-1/2}$

$$h_i(r) = \beta_i \frac{(1-r^2)L_p(r)}{(r-\zeta_1)(r-r_i)}$$
$$g_i(r) = \gamma_i \frac{L_p(r)}{r-\zeta_i}$$

▶ where $L_p(r)$ is the Legendre polynomial of order p, ζ_i are the 'zeroes' of Legendre polynomial and $r_i = -1, \zeta_i \neq \zeta_1, 1$.

Radial Discretisation with the COOL method

> Hybrid finite element radial discretisation used till now in TERP-SICHORE corresponds to the p = 1 choice in the COOL method

$$X_{\ell}(s_{j-1/2}) \simeq \frac{1}{2}(X_{\ell}^{j} + X_{\ell}^{j-1})$$
$$\frac{\partial X_{\ell}}{\partial s} \simeq \frac{1}{\Delta s}(X_{\ell}^{j} - X_{\ell}^{j-1})$$
$$Y_{\ell}(s_{j-1/2}) \equiv Y_{\ell}^{j}$$

▷ In the radial domain $s_{j-1} \leq s \leq s_j$ for arbitrary choice of p

$$\begin{aligned} X_{\ell}(s) &\simeq h_{1}(r)X_{\ell}^{j-1} + \sum_{i=2}^{p} h_{i}(r)X_{\ell}(s(r=\zeta_{i})) + h_{p+1}(r)X_{\ell}^{j} \\ \frac{dX_{\ell}}{ds} &\simeq \frac{2}{\Delta s} \Big(\frac{dh_{1}}{dr}X_{\ell}^{j-1} + \sum_{i=2}^{p} \frac{dh_{i}}{dr}X_{\ell}(s(r=\zeta_{i})) + \frac{dh_{p+1}}{dr}X_{\ell}^{j} \Big) \\ Y_{\ell}(s) &= \sum_{i=1}^{p} g_{i}(r)Y_{\ell}(s(r=\zeta_{i})) \end{aligned}$$

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